

SureLog-iPZIG

Global perspective. Independent thinking.

At-Bit Inclination and Image Gamma Ray Service

ApplicAtions

- Real-time geosteering
- Horizontal, ERD, and directional drilling
- Steering within formations with dipping heds
- Casing point selection by detecting formation changes at the bit

REnEFits

- Optimal well placement in reservoirs
- Accelerated production
- Reduced well tortuosity and dogleg severity
- Early bed boundary detection

FEAturEs

- Inclination and natural gamma ray measurements situated at the bit
- Azimuthal natural gamma ray image measurements at bit
- Wireless electromagnetic communication between upper and lower subs with data transmitted real-time via PathFinder MWD system
- Compatible with positive displacement motors and rotary steerable tools
- Stand-alone battery operated electronics
- Compatible with all mud types

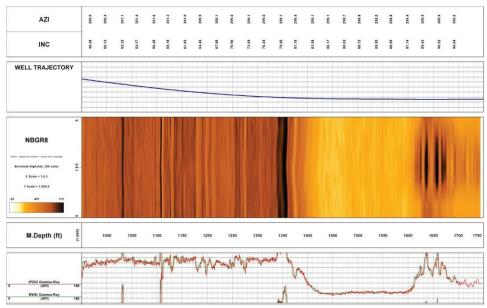
The SureLogTM tool family includes the iPZIG* system. The iPZIG tool provides at-bit gamma ray images along with traditional natural gamma ray measurements, dynamic inclination, RPM and temperature. The at-bit gamma ray image can be provided in sectors for superior real-time geosteering capabilities that include formation bed dip calculations.

Operating directly behind the drill bit, the iPZIG at-bit inclination and gamma ray service provides real-time measurements that reduce directional drilling risk in critical hole sections. The early indication of changes in lithology, delivered by the gamma ray log, helps to accurately land horizontal wells.

Designed to operate as two separate subs, a lower sub, located directly above the drill bit, acquires data and transmits data to the upper sub, located above the drilling mud motor. The upper sub provides communication to measurement/logging-while-drilling systems.

The iPZIG can accommodate flexible bottomhole assembly (BHA) designs, and is compatible with any drilling mud motor. iPZIG provides the closest to the bit sensor offsets available in the industry and is the only tool to provide both gamma and inclination at the bit. These measurements are used to help determine well path placement and de-termine position in real-time while drilling.

The iPZIG sub is an accurate, cost effective geosteering solution whether drilling for optimum reservoir drainage, setting casing, or just to determine position real-time while drilling.



iPZIG eight sector gamma ray image and comparison of near-bit total gamma ray measurement with conventional MWD gamma ray logged through build and horizontal sections of the well.





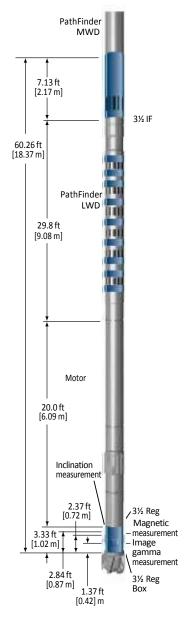
Nominal OD, in [mm]	4¾ [120.7]	6¾[171.5]	8 [203.2]
Maximum OD, in [mm]	5.25 [133.4]	7.25 [184.2]	8.25 [209.6]
UXM tool joint	3 ½ IF Box/Pin	5 ½ FH Box/Pin	5½ IF Box/Pin
LXM tool joint	3 ½ Reg Pin/Box	4 ½ Reg Pin/Box	65/8 Reg Pin/Box
UXM length, ft [m]	7.13 [2.17]	5.92 [1.81]	5.92 [1.81]
LXM length, ft [m]	3.33 [1.02]	3.66 [1.12]	3.66 [1.12]
UXM weight, lbm [kg]	375 [170]	620 [282]	756 [344]
LXM weight, lbm [kg]	210 [95]	370 [168]	510 [232]
LXM equivalent stiffness, in [mm]	4.43 [112.5] ID/ 2.25 [57.2]OD	5.99 [152.1] ID/ 2.81 [71.4]OD	6.96 [176.8] OD/ 2.81 [71.4] ID
LXM avg. moment of intertia, in 4 [mm4]	17.6 [722.7]	60 [2,463.7]	112 [4,598.9]
UXM equivalent stiffness, in [mm]	4.52 [114.8] ID/ 2.25 [57.2]OD	6.34 [161.0] ID/ 2.81 [71.4]OD	7.34 [186.4] OD/ 2.81 [71.4] ID
UXM avg. moment of intertia, in 4 [mm 4]	19.2 [788.4]	76.2 [3,128.9]	122 [5,099.6]
tool Joints, 43/4 in		toolJoints, 63/4in	
API 3 ½ IF, field (UXM)		API 5 ½ FH, field (UXM)	
Makeup torque, ft.lbf [N.m]	9,000 [12,202]	Makeup torque, ft.lbf [N.m]	25,000 [33,895
Bending-strength ratio	2.06	Bending-strength ratio	1.8
API 3 ½, Reg (LXM)		API 4 ½ Reg, (LXM)	
Makeup torque, ft.lbf [N.m]	8,000 [10,847]	Makeup torque, ft.lbf [N.m]	24,000 [32,540
Bending-strength ratio	4.41	Bending-strength ratio	4.0
tool Joints, 8 in			
API 5 ½ IF, field (UXM)			
Makeup torque, ft.lbf [N.m]	38,000 [51,520]		
Bending-strength ratio	2.35		
API 6 5/8 Reg (LXM)			
Makeup torque, ft.lbf [N.m]	38,000 [51,520]		
Bending-strength ratio	3.48		
operating limits [†]			
Max.dogleg,rotating,deg/ft	17/100	10/100	10/100
Max. dogleg, sliding, deg/ft	31/100	16/100	16/100
Max. tension, lbf [kg]	263,000 [119,295]	400,000 [181,437]	450,000 [204,117]
Max. torque, ft.lbf [N.m]	9,000 [12,203]	23,000 [31,184]	35,000 [47,453]
Max. operating temp., degF [degC] **	302 [150], 350 [175]	302 [150], 350 [175]	302 [150], 350 [175]
Measurement specifications			
Gamma ray sensor offset, in [mm]	16.69 [423.9]	21.00 [533.4]	21.29 [540.8]
Inclination sensor offset, in [mm]	34.1[866.1]	38.55 [979.2]	39.14[994.2]
Inclination range, deg	5 to 180	Inclination accuracy, deg	0
		+ " "	

 $^{{}^{\}dagger} Contact\, APS\, Technology\, for\, limitations\, in\, specific \, applications.$



 $^{^{\}dagger\dagger} Standard tool \, configuration \, 32 to \, 302 \, deg F \, [0 to \, 150 \, deg C], optional \, Survivor \, Series \, rating \, 32 to \, 350 \, deg F \, [0 to \, 175 \, deg C].$

At-Bit Inclination and Image Gamma Ray Service



Tool	ς	pecifications
100		pecinications

Tool Specifications Nominal OD, in [mm]	43/4 [120.7]	Max.OD, in [mm]	5.25 [133.4]
Internal diameters, in [n		Internal diameters, in [mn	
UXM	3.50 [88.9], 2.80 [71.1], 2.50 [63.5]	LXM	3.80 [96.5], 1.10 in [27.9]
Length,ft[m]		Length,ft[m]	
UXM	7.13 [2.17]	LXM	3.33 [1.02]
Tool joints, box/pin		Tool joints, box/pin	
UXM	3½ IF	LXM	3½ Reg
Weight, lbm [kg]		Weight, lbm [kg]	
UXM	375 [170]	LXM	210 [95]
UXM Equivalent stiff- ness, in [mm]	4.52 [114.8] OD/2.25 [57.2] ID	UXM Avg. moment of inertia, in ⁴ [cm ⁴]	19.2 [788.4]
LXM Equivalent stiff- ness, in [mm]	4.43 [112.5 OD/2.25 [57.2] ID	LXM Avg. moment of inertia, in ⁴ [cm ⁴]	17.6 [722.7]
Tool Joint Specifications			
API 3½ IF, field (UXM)			
Makeup torque, lbf	f.ft [N.m]		9,000 [12,202]
Bending-strength	n ratio		2.35
API3½ Reg, (LXM)			
Makeup torque, lbf	f.ft [N.m]		8,000 [10,847]
Bending-strength	n ratio		4.41
Sensor Measurement Po	ints		
lmage gamma measur	rement, ft [m]		1.37 [0.42]
Magnetic measurement, ft [m]			2.37 [0.72]
Inclination measureme	ent, ft [m]		2.84 [0.87]
Operating Specifications	S		
Max. dogleg, rotating, o/100 ft	17	Max. dogleg,sliding, o/100 ft	3
Max. tension, lb [kg]	263,000 [119,295]	Maximum torque, lbf.ft [N.m]	9,000 [12,203]
Max. temp.,	302 [150], 350 [175] [†]	Flow rates,	125 to 375 [0.473

Note: All dimensions are nominal. Configuration options are available. Tool drawing is not to scale.

[†]Standard tool configuration 32 to 302 degF [0 to 150 degC], optional Survivor Series rating 32 to 350 degF [0 to 175 degC].



At-Bit Inclination and Image Gamma Ray Service

PathFinder MWD	
5.92 ft [1.81 m] 54.58 ft [16.64 m] PathFinder	
25.0 ft [7.62] m	
Motor	— 5½ FH
20.0 ft [6.09 m] Inclination measurement	
2.73 ft [0.83 m]	4½ Reg Pin Magnetic measurement Image gamma measurement
3.66 ft 1.73 ft [1.12 m] [0.53 m] 3.22 ft [0.98 m]	4½ Reg Box

Tool Specifications			
Nominal OD, in [mm]	63/4 [171.5]	Max.OD, in [mm]	7.25 [184.2]
Internal diameters, in [mm]		Internal diameters, in [mm]	
UXM	5.10[129.5],4.00 [101.6], 3.50 [88.9]	LXM	5.30 [134.6], 2.00 [27.9]
Length,ft[m]		Length,ft[m]	
UXM	5.92 [1.81]	LXM	3.66 [1.12]
Tool joints, box/pin		Tool joints, box/pin	
UXM	5½ FH	LXM	4½ Reg
Weight, lbm [kg]		Weight, lbm [kg]	
UXM	620 [282.0]	LXM	370 [168.0]
UXM equivalent stiff- ness, in [mm]	6.34 [161.0] OD/2.81 [71.4] ID	UXMavg.moment of inertia, in ⁴ [cm ⁴]	76.2 [3,128.9]
LXM equivalent stiff- ness, in [mm]	5.99 [152.1] OD/2.81 [71.4]	LXM avg. moment of inertia, in ⁴ [cm ⁴]	60.0 [2,463.7]
Sensor Measurement Point	S		
lmage gamma measurer	ment, ft [m]		1.73 [0.53]
Magnetic measurement, ft [m]			2.73 [0.83]
Inclination measurement, ft [m]			3.22 [0.98]
Tool Joint Specifications			
API 5½ FH, field (UXM)			
Makeup torque, lbf.ft	[N.m]		25,000 [33,895]
Bending-strength ratio			1.81
API4½ Reg, (LXM)			
Makeup torque, lbf.ff	[N.m]		24,000 [32,540]
Bending-strength r	atio		4.02
Operating Specifications			
Max. dogleg, rotating, o/100 ft	10	Max. dogleg,sliding, o/100ft	16

Note: All dimensions are nominal. Configuration options are available. Tool drawing is not to scale.

302 [150], 350 [175][†]

400,000 [181,437]

Max. tension, lb [kg]

Max. temp.,

degF [degC]

†Standard tool configuration 32 to 302 degF [0 to 150 degC], optional Survivor Series rating 32 to 350 degF [0 to 175 degC].

Maximum torque,

galUS/min [m³/min]

lbf.ft [N.m]

Flow rates,



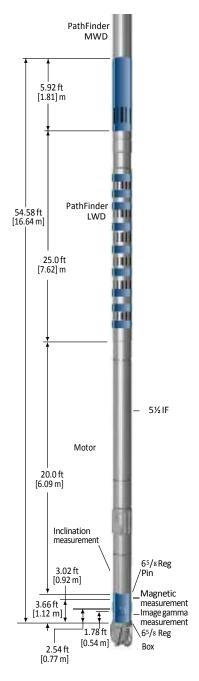
38,000 [51,520]

250 to 750 [0.946

to 2.839]

Mechanical Specifications

At-Bit Inclination and Image Gamma Ray Service



Nominal OD, in [mm]	8 [171.5]	Max.OD,in [mm]	8.25 [209.6]
Internal diameters, in [mn	n]	Internal diameters, in [m	m]
UXM	5.10[129.5], 4.00 [101.6], 3.50 [88.9]	LXM	5.30 [134.6], 2.00 [27.9]
Length,ft[m]		Length,ft[m]	
UXM	5.92 [1.81]	LXM	3.66 [1.12]
Tool joints, box/pin		Tool joints, pin/box	
UXM	5½IF	LXM	6 ⁵ /8 Reg
Weight,lbm[kg]		Weight, lbm [kg]	
UXM	756 [344]	LXM	510 [232]
UXM equivalent stiff- ness, in [mm]	7.34 [186.4] OD/2.81 [71.4] ID	UXM avg. moment of inertia, in ⁴ [cm ⁴]	122.0 [5,099.6]
LXM equivalent stiff-	6.99 [176.8] OD/2.81	LXMavg.moment of	112 [4,598.9]
ness, in [mm]	[71.4]	inertia, in ⁴ [cm ⁴]	
Sensor Measurement Point	S		
lmage gamma measurer	ment, ft [m]		1.78 [0.54]
Magnetic measurement,	ft [m]		2.54 [0.77]
Inclination measurement	t, ft [m]		3.02 [0.92]
Tool Joint Specifications			
API 5½ IF, field (UXM)			
Makeuptorque, lbf.ft	[N.m]		38,000 [51,520]
Bending-strength r	atio		2.35
API 6 ⁵ /8 Reg, (LXM)			
Makeuptorque,lbf.ft	[N.m]		38,000 [51,520]
Bending-strength r	atio		4.38
Operating Specifications			
Max. dogleg, rotating, o/100ft	10	Max.dogleg,sliding, o/100ft	16
Max. tension, lb [kg]	450,000 [204,117]	Maximum torque, lbf.ft [N.m]	35,000 [47,453]
Max. temp., degF [degC]	302 [150], 350 [175]††	Flow rates, galUS/min [m³/min]	250 to 750 [0.946 to 2.839]

Note: All dimensions are nominal. Configuration options are available. Tool drawing is not to scale.

†Standard tool configuration 32 to 302 degF [0 to 150 degC], optional Survivor Series rating 32 to 350 degF [0 to 175 degC].

