

SureLog-iPZIG

Global perspective. Independent thinking.

At-Bit Inclination and Image Gamma Ray Service

APPLICATIONS

- Real-time geosteering
- Horizontal, ERD, and directional drilling
- Steering within formations with dipping heds
- Casing point selection by detecting formation changes at the bit

BENEFITS

- Optimal well placement in reservoirs
- Accelerated production
- Reduced well tortuosity and dogleg severity
- Early bed boundary detection

FEATURES

- Inclination and natural gamma ray measurements situated at the bit
- Azimuthal natural gamma ray image measurements at bit
- Wireless electromagnetic communication between upper and lower subs with data transmitted real-time via PathFinder MWD system
- Compatible with positive displacement motors and rotary steerable tools
- Stand-alone battery operated electronics
- Compatible with all mud types

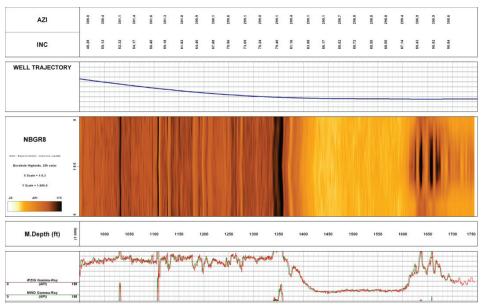
The SureLogTM tool family includes the iPZIG* system. The iPZIG tool provides at-bit gamma ray images along with traditional natural gamma ray measurements, dynamic inclination, RPM and temperature. The at-bit gamma ray image can be provided in sectors for superior real-time geosteering capabilities that include formation bed dip calculations.

Operating directly behind the drill bit, the iPZIG at-bit inclination and gamma ray service provides real-time measurements that reduce directional drilling risk in critical hole sections. The early indication of changes in lithology, delivered by the gamma ray log, helps to accurately land horizontal wells.

Designed to operate as two separate subs, a lower sub, located directly above the drill bit, acquires data and transmits data to the upper sub, located above the drilling mud motor. The upper sub provides communication to measurement/logging-while-drilling systems.

The iPZIG can accommodate flexible bottomhole assembly (BHA) designs, and is compatible with any drilling mud motor. iPZIG provides the closest to the bit sensor offsets available in the industry and is the only tool to provide both gamma and inclination at the bit. These measurements are used to help determine well path placement and de-termine position in real-time while drilling.

The iPZIG sub is an accurate, cost effective geosteering solution whether drilling for optimum reservoir drainage, setting casing, or just to determine position real-time while drilling.



iPZIG eight sector gamma ray image and comparison of near-bit total gamma ray measurement with conventional MWD gamma ray logged through build and horizontal sections of the well.



iPZIG

Name and OD in faces.	4.2/ [400.7]	0.2/[174.5]	0 [000 0]
Nominal OD, in [mm]	4 ¾ [120.7]	6 ¾ [171.5]	8 [203.2]
Maximum OD, in [mm]	5.25 [133.4]	7.25 [184.2]	8.25 [209.6]
UXM tool joint	3 ½ IF Box/Pin	5 ½ FH Box/Pin	5 ½ IF Box/Pin
LXM tool joint	3 ½ Reg Pin/Box	4 ½ Reg Pin/Box	6 5/8 Reg Pin/Box
UXM length, ft [m]	7.13 [2.17]	5.92 [1.81]	5.92 [1.81]
LXM length, ft [m]	3.33 [1.02]	3.66 [1.12]	3.66 [1.12]
UXM weight, lbm [kg]	375 [170]	620 [282]	756 [344]
LXM weight, lbm [kg]	210 [95]	370 [168]	510 [232]
LXM equivalent stiffness, in [mm]	4.43 [112.5] ID/ 2.25 [57.2]OD	5.99 [152.1] ID/ 2.81 [71.4]OD	6.96 [176.8] OD/ 2.81 [71.4] ID
LXM avg. moment of intertia, in ⁴ [mm ⁴]	17.6 [722.7]	60 [2,463.7]	112 [4,598.9]
UXM equivalent stiffness, in [mm]	4.52 [114.8] ID/ 2.25 [57.2]OD	6.34 [161.0] ID/ 2.81 [71.4]OD	7.34 [186.4] OD/ 2.81 [71.4] ID
UXM avg. moment of intertia, in ⁴ [mm ⁴]	19.2 [788.4]	76.2 [3,128.9]	122 [5,099.6]
Tool Joints, 4 ¾ in		Tool Joints, 6 ¾ in	
API 3 ½ IF, field (UXM)		API 5 ½ FH, field (UXM)	
Makeup torque, ft.lbf [N.m]	9,000 [12,202]	Makeup torque, ft.lbf [N.m]	25,000 [33,895
Bending-strength ratio	2.06	Bending-strength ratio	1.8
API 3 ½, Reg (LXM)		API 4 ½ Reg, (LXM)	
Makeup torque, ft.lbf [N.m]	8,000 [10,847]	Makeup torque, ft.lbf [N.m]	24,000 [32,540
Bending-strength ratio	4.41	Bending-strength ratio	4.0
Tool Joints, 8 in			
API 5 ½ IF, field (UXM)			
Makeup torque, ft.lbf [N.m]	38,000 [51,520]		
Bending-strength ratio	2.35		
API 6 5/8 Reg (LXM)			
Makeup torque, ft.lbf [N.m]	38,000 [51,520]		
Bending-strength ratio	3.48		
Operating Limits [†]			
Max. dogleg, rotating, deg/ft	17/100	10/100	10/100
Max. dogleg, sliding, deg/ft	31/100	16/100	16/100
Max. tension, lbf [kg]	263,000 [119,295]	400,000 [181,437]	450,000 [204,117]
Max. torque, ft.lbf [N.m]	9,000 [12,203]	23,000 [31,184]	35,000 [47,453]
Max. operating temp., degF [degC] ††	302 [150], 350 [175]	302 [150], 350 [175]	302 [150], 350 [175]
Measurement Specifications			
Gamma ray sensor offset, in [mm]	16.69 [423.9]	21.00 [533.4]	21.29 [540.8]
Inclination sensor offset, in [mm]	34.1 [866.1]	38.55 [979.2]	39.14 [994.2]
Inclination range, deg	5 to 180	Inclination accuracy, deg	0.
At bit rpm	30 to 450	Total gamma range, API	0 to 1,20

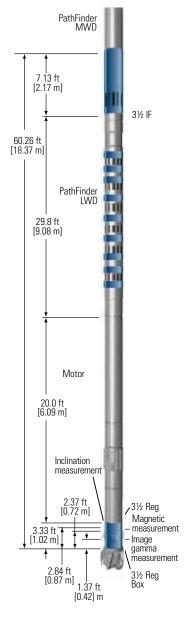
 $^{^{\}dagger}\text{Contact}$ APS Technology for limitations in specific applications.

^{††}Standard tool configuration 32 to 302 degF [0 to 150 degC], optional Survivor Series rating 32 to 350 degF [0 to 175 degC].



Mechanical Specifications

At-Bit Inclination and Image Gamma Ray Service



-	•		
I nni	Sn	つけいつ	ations
	UP		uuuuis

4¾ [120.7]	Max. OD, in [mm]	5.25 [133.4]
m]	Internal diameters, in [mi	m]
3.50 [88.9], 2.80 [71.1],	LXM	3.80 [96.5], 1.10
2.50 [63.5]		in [27.9]
	Length, ft [m]	
7.13 [2.17]	LXM	3.33 [1.02]
	Tool joints, box/pin	
3½ IF	LXM	3½ Reg
	Weight, Ibm [kg]	
375 [170]	LXM	210 [95]
4.52 [114.8] OD/2.25	UXM Avg. moment of	19.2 [788.4]
[57.2] ID	inertia, in ⁴ [cm ⁴]	
4.43 [112.5 OD/2.25	LXM Avg. moment of	17.6 [722.7]
[57.2] ID	inertia, in ⁴ [cm ⁴]	
t [N.m]		9,000 [12,202]
tio		2.35
t [N.m]		8,000 [10,847]
tio		4.41
ıts		
ment, ft [m]		1.37 [0.42]
t, ft [m]		2.37 [0.72]
nt, ft [m]		2.84 [0.87]
17	Max. dogleg,sliding,	31
	°/100 ft	
263,000 [119,295]	Maximum torque,	9,000 [12,203]
	lbf.ft [N.m]	
302 [150], 350 [175] [†]	Flow rates,	125 to 375 [0.473
	galUS/min [m³/min]	to 1.420]
	m] 3.50 [88.9], 2.80 [71.1], 2.50 [63.5] 7.13 [2.17] 3½ IF 375 [170] 4.52 [114.8] OD/2.25 [57.2] ID 4.43 [112.5 OD/2.25 [57.2] ID t [N.m] tio tt [N.m] tio nts ment, ft [m] nt, ft [m] 17 263,000 [119,295]	Internal diameters, in [m] 3.50 [88.9], 2.80 [71.1], LXM Length, ft [m] T.13 [2.17] LXM Tool joints, box/pin 3½ IF LXM Weight, lbm [kg] LXM Weight, lbm [kg] LXM LXM

Note: All dimensions are nominal. Configuration options are available. Tool drawing is not to scale.

[†]Standard tool configuration 32 to 302 degF [0 to 150 degC], optional Survivor Series rating 32 to 350 degF [0 to 175 degC].



At-Bit Inclination and Image Gamma Ray Service

PathFinder MWD 5.92 ft [1.81 m] 54.58 ft [16.64 m] PathFinder LWD 25.0 ft [7.62] m — 5½ FH Motor 20.0 ft [6.09 m] Inclination measurement 2.73 ft [0.83 m] 4½ Reg Pin

Nominal OD, in [mm]	6¾ [171.5]	Max. OD, in [mm]	7.25 [184.2]
Internal diameters, in [mr	n]	Internal diameters, in [mm	
UXM	5.10 [129.5] , 4.00 [101.6], 3.50 [88.9]	LXM	5.30 [134.6] 2.00 [27.9]
Length, ft [m]		Length, ft [m]	
UXM	5.92 [1.81]	LXM	3.66 [1.12]
Tool joints, box/pin		Tool joints, box/pin	
UXM	5½ FH	LXM	4½ Reg
Weight, Ibm [kg]		Weight, Ibm [kg]	
UXM	620 [282.0]	LXM	370 [168.0]
UXM equivalent stiff-	6.34 [161.0] OD/2.81	UXM avg. moment of	76.2 [3,128.9]
ness, in [mm]	[71.4] ID	inertia, in ⁴ [cm ⁴]	
LXM equivalent stiff-	5.99 [152.1] OD/2.81	LXM avg. moment of	60.0 [2,463.7
ness, in [mm]	[71.4]	inertia, in ⁴ [cm ⁴]	
Sensor Measurement Point	s		
lmage gamma measuren	nent, ft [m]		1.73 [0.53
Magnetic measurement,	ft [m]		2.73 [0.83]
Inclination measuremen	t, ft [m]		3.22 [0.98]
Tool Joint Specifications			
API 5½ FH, field (UXM)			
Makeup torque, lbf.ft	[N.m]		25,000 [33,895]
Bending-strength rati	io		1.81
API 4½ Reg, (LXM)			
Makeup torque, lbf.fr	t [N.m]		24,000 [32,540
Bending-strength rati	io		4.02
Operating Specifications			
Max. dogleg, rotating,	10	Max. dogleg,sliding,	16

Note: All dimensions are nominal. Configuration options are available. Tool drawing is not to scale.

302 [150], 350 [175][†]

400,000 [181,437]

Max. tension, lb [kg]

Max. temp.,

degF [degC]

†Standard tool configuration 32 to 302 degF [0 to 150 degC], optional Survivor Series rating 32 to 350 degF [0 to 175 degC].

Maximum torque,

galUS/min [m3/min]

lbf.ft [N.m]

Flow rates,



38,000 [51,520]

250 to 750 [0.946

to 2.839]

[0.53 m]

3.66 ft [1.12 m] Magnetic

gamma

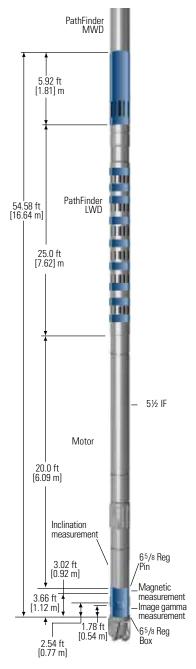
4½ Reg

measurement

8.25 [209.6]

At-Bit Inclination and Image Gamma Ray Service

Tool Specifications



		1349.4
Internal diameters, in [mm]		Internal diameters, in [mm]
Nominal OD, in [mm]	8 [171.5]	Max. OD, in [mm]

	internar diameters, in tillin	J	internal diameters, in [illin]	
	UXM	5.10 [129.5] , 4.00	LXM	5.30 [134.6],
_		[101.6], 3.50 [88.9]		2.00 [27.9]
	Length, ft [m]		Length, ft [m]	
	UXM	5.92 [1.81]	LXM	3.66 [1.12]
	Tool joints, box/pin		Tool joints, pin/box	
	UXM	5½ IF	LXM	6 ⁵ /8 Reg
	Weight, lbm [kg]		Weight, Ibm [kg]	
_	UXM	756 [344]	LXM	510 [232]
	UXM equivalent stiff-	7.34 [186.4] OD/2.81	UXM avg. moment of	122.0 [5,099.6]
_	ness, in [mm]	[71.4] ID	inertia, in ⁴ [cm ⁴]	
	LXM equivalent stiff-	6.99 [176.8] OD/2.81	LXM avg. moment of	112 [4,598.9]
	ness, in [mm]	[71.4]	inertia, in ⁴ [cm ⁴]	

Sensor Measurement Points

Image gamma measurement, ft [m]	1.78 [0.54]
Magnetic measurement, ft [m]	2.54 [0.77]
Inclination measurement, ft [m]	3.02 [0.92]

Tool Joint Specifications

API 5½ IF, field (UXM)	
Makeup torque, lbf.ft [N.m]	38,000 [51,520]
Bending-strength ratio	2.35
API 65/8 Reg, (LXM)	
Makeup torque, lbf.ft [N.m]	38,000 [51,520]
Bending-strength ratio	4.38

Operating Specifications

Max. dogleg, rotating, °/100 ft	10	Max. dogleg, sliding, °/100 ft	16
Max. tension, lb [kg]	450,000 [204,117]	Maximum torque, lbf.ft [N.m]	35,000 [47,453]
Max. temp., degF [degC]	302 [150], 350 [175] ^{††}	Flow rates, galUS/min [m³/min]	250 to 750 [0.946 to 2.839]

Note: All dimensions are nominal. Configuration options are available. Tool drawing is not to scale.

†Standard tool configuration 32 to 302 degF [0 to 150 degC], optional Survivor Series rating 32 to 350 degF [0 to 175 degC].

